

Advances in Morphological Neural Networks: Training, Pruning and Enforcing Shape Constraints

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Binary Morphological Classifiers trained via Difference-of-Convex optimization

→ Extended to multiclass problems

Sparsity of Morphological Neural Nets

→ Showed quantitatively and qualitatively superior compression ability compared to ReLU FeedForward nets

Monotonic function approximation

→ Improved with softened morphological operators via Maslov Dequantization

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Background Concepts

Training Morphological Neural Networks

Pruning Morphological Neural Networks

Enforcing Shape Constraints

Morphological Operators for Vectors

$$\text{Dilation:} \quad \delta_w(\mathbf{x}) = w_0 \vee \left(\bigvee w_i + x_i \right)$$

$$\text{Erosion:} \quad \varepsilon_m(\mathbf{x}) = m_0 \wedge \left(\bigwedge m_i + x_i \right)$$

Softmax and Softmin scalar operations via Maslov Dequantization¹

($h > 0$: temperature parameter)

$$\text{max:} \quad x \vee y \quad \longrightarrow \quad x \vee_h y = h \log(e^{x/h} + e^{y/h}) \quad : \text{softmax}$$

$$\text{min:} \quad x \wedge y \quad \longrightarrow \quad x \wedge_h y = -h \log(e^{-x/h} + e^{-y/h}) \quad : \text{softmin}$$

Morphological Operators for Vectors ↘

Softened Morphological operators

Softmax and Softmin scalar operations ↗

¹Litvinov, G. L. "Maslov dequantization, idempotent and tropical mathematics: A brief introduction". In: *Journal of Mathematical Sciences* 140.3 (2007), pp. 426–444.

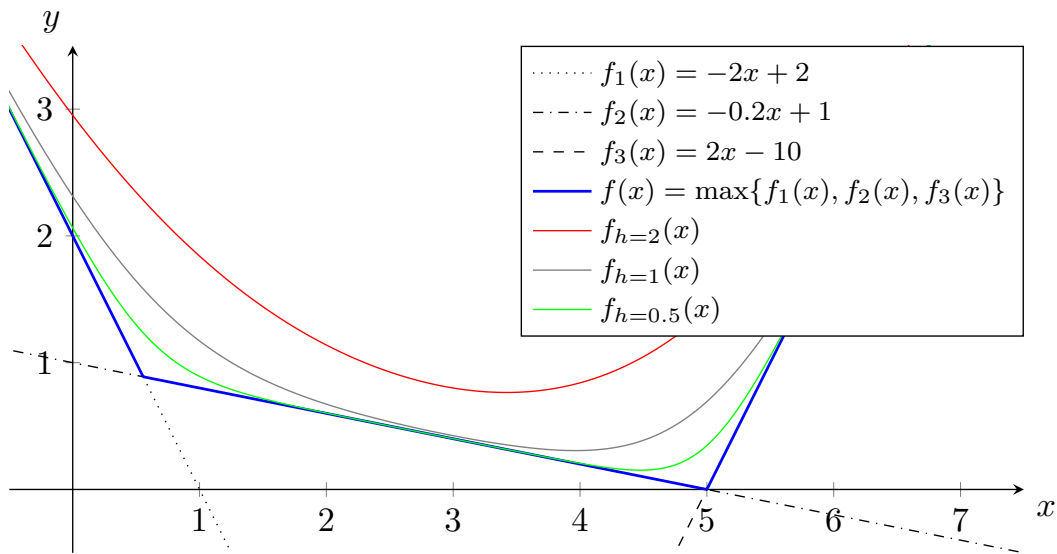


Figure: Effect of temperature parameter h

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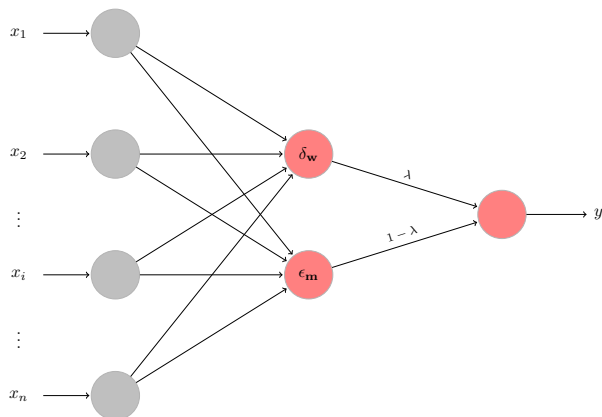
Background Concepts

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Dilation-Erosion Perceptron (DEP)



Convex combination of one dilation and one erosion neuron:

$$y = f(\mathbf{x}) = \lambda \delta_{\mathbf{w}}(\mathbf{x}) + (1 - \lambda) \epsilon_{\mathbf{m}}(\mathbf{x})$$

Dilation-Erosion Perceptron (DEP) [cont.]

$$\begin{aligned}y = f(\mathbf{x}) &= \lambda\delta_w(\mathbf{x}) + (1 - \lambda)\epsilon_m(\mathbf{x}) = \lambda\delta_w(\mathbf{x}) - (1 - \lambda)[- \epsilon_m(\mathbf{x})] \\ &= \text{convex} - (-\text{concave}) \\ &= \text{convex} - (\text{convex})\end{aligned}$$

Training as Difference-of-Convex Program^{1,2,3}

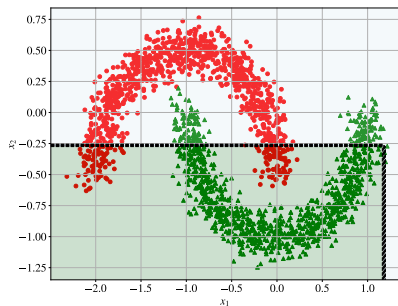
$$\begin{aligned}\text{minimize} \quad & \sum_{i=1}^N v_i \max\{0, \xi_i\} \\ \text{subject to} \quad & \lambda\delta_w(\mathbf{x}_i) + (1 - \lambda)\epsilon_m(\mathbf{x}_i) \geq -\xi_i \quad \forall \mathbf{x}_i \in \mathcal{P}, \\ & \lambda\delta_w(\mathbf{x}_i) + (1 - \lambda)\epsilon_m(\mathbf{x}_i) \leq +\xi_i \quad \forall \mathbf{x}_i \in \mathcal{N}\end{aligned}$$

¹Charisopoulos, V. and Maragos, P. "Morphological Perceptrons: Geometry and Training Algorithms". In: *Mathematical Morphology and Its Applications to Signal and Image Processing (Proc. ISMM 2017)*. Vol. 10225. LNCS. Springer, 2017, pp. 3–15. ISBN: 978-3-319-57240-6.

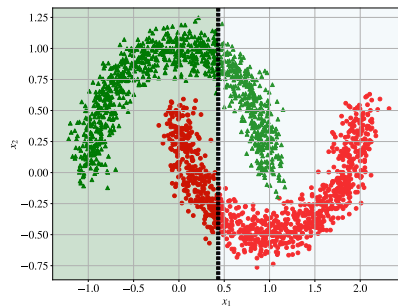
²Yuille, A. L. and Rangarajan, A. "The Concave-Convex Procedure". In: *Neural computation* 15.4 (2003), pp. 915–936.

³Lipp, T. and Boyd, S. "Variations and extension of the convex–concave procedure". In: *Optimization and Engineering* 17.2 (2016), pp. 263–287.

What is the effect of $\mathcal{N} \rightleftharpoons \mathcal{P}$?



(a) correct labels



(b) reversed labels

Figure: Double Moons example¹.

Reduced Ordering:

Let R be a nonempty set, \mathcal{L} be a complete lattice and $\rho : R \rightarrow \mathcal{L}$ be a surjective mapping. A reduced ordering is defined as: $\mathbf{x} \leq_{\rho} \mathbf{y} \Leftrightarrow \rho(\mathbf{x}) \leq \rho(\mathbf{y}), \forall \mathbf{x}, \mathbf{y} \in R$.

¹Valle, M. E. "Reduced Dilation-Erosion Perceptron for Binary Classification". In: *Mathematics* 8.4 (2020). ISSN: 2227-7390.

Extending to multiclass problems

one-versus-the-rest

- ▶ positive class \mathcal{C}_k , negative class \mathcal{C}_{-k}
- ▶ imbalance: $|\mathcal{C}_k| \simeq \frac{N}{K} \ll |\mathcal{C}_{-k}| \simeq \frac{(K-1)N}{K}$

one-versus-one

- ▶ $\frac{K(K-1)}{2}$ distinct classifiers must be trained
- ▶ majority (hard) vote of all classifiers

Method

Use a bagging classifier for n Radial Basis Function (RBF) kernel estimators.

	MNIST	FashionMNIST
$n = 5$	97.72 ± 0.01	88.21 ± 0.01
$n = 10$	97.72 ± 0.01	88.07 ± 0.01
$n = 15$	97.67 ± 0.01	88.11 ± 0.01
$n = 20$	97.64 ± 0.01	88.12 ± 0.01

Table: Results of Bagging *multiclass* r-DEP with n RBF kernels.

Performance similar architectures trained via Gradient Descent

CCP training is very robust

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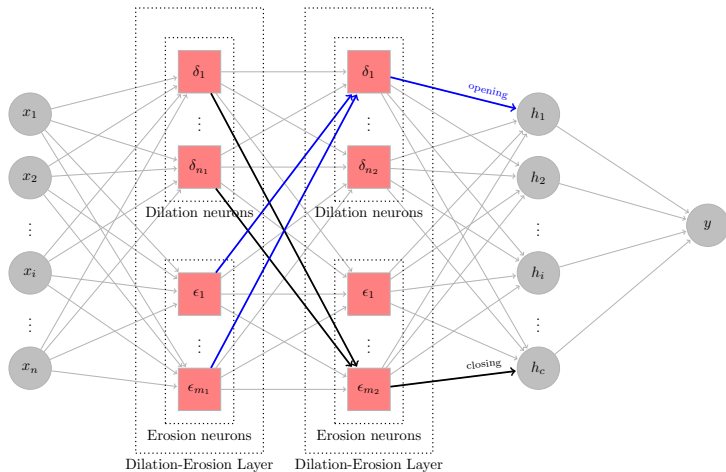


Figure: Dense Morphological Network with 2 hidden layers¹

Focus is on sparsity. Apply ℓ_1 pruning.

¹Mondal, R., Santra, S., and Chanda, B. "Dense Morphological Network: An Universal Function Approximator". In: *arXiv* (2019). URL: <http://arxiv.org/abs/1901.00109>.

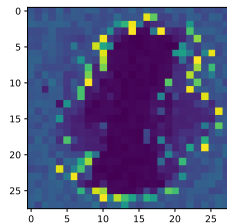
		Adaptive Momentum Estimation				Stochastic Gradient Descent			
p		δ	ε	(δ, ε)	FF-ReLU	δ	ε	(δ, ε)	FF-ReLU
MNIST	100%	97.62	96.17	97.95	98.13	94.86	93.36	96.07	98.16
	75%	97.62	96.18	97.93	98.15	94.86	93.36	96.07	98.12
	50%	97.62	96.22	97.90	98.17	94.86	93.37	96.07	98.08
	25%	97.62	96.09	97.87	97.51	94.86	93.40	96.06	98.01
	10%	97.62	95.78	97.74	93.38	94.86	93.38	96.09	96.67
	7.5%	97.62	95.42	97.76	90.17	94.86	93.38	96.10	95.56
	5%	97.62	94.51	97.66	83.39	94.86	93.40	96.10	92.96
	2.5%	97.62	93.43	97.37	68.93	94.86	93.39	96.09	80.48
	1%	97.62	91.17	97.08	44.22	94.86	93.38	96.08	58.07
FashionMNIST	100%	86.31	86.82	88.32	88.82	82.06	85.23	86.21	87.79
	75%	86.30	86.81	88.30	88.88	82.00	85.23	86.21	87.75
	50%	86.22	86.80	88.33	88.18	82.05	85.25	86.20	87.19
	25%	85.95	86.85	88.31	82.15	81.90	85.26	86.28	84.35
	10%	85.58	86.27	88.05	65.89	81.67	85.27	86.23	73.22
	7.5%	85.47	86.15	87.99	57.93	81.63	85.27	86.21	63.95
	5%	85.37	85.81	87.76	49.12	81.52	85.24	86.22	47.73
	2.5%	84.91	85.47	87.56	42.48	81.14	85.26	86.22	38.84
	1%	81.14	84.86	86.85	28.13	80.68	85.27	86.18	35.46

Table: Accuracy of pruned networks on the MNIST and FashionMNIST datasets.

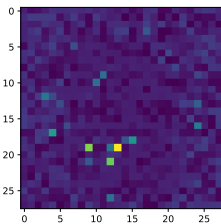
Models: δ \rightarrow only dilation neurons, ε \rightarrow only erosion, (δ, ε) \rightarrow split equally, FF-ReLU \rightarrow FeedForward NN with ReLU.

shades of red showcase the degree of (severe) deterioration in accuracy green indicates the absence of performance loss

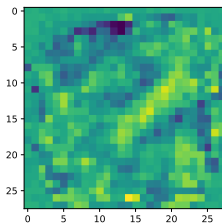
Qualitative Perspective



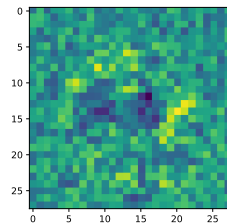
(a) (δ, ϵ) - Adam



(b) (δ, ϵ) - SGD



(c) FF-ReLU - Adam



(d) FF-ReLU - SGD

Figure: Examples of hidden layer activations for various models (MNIST dataset).

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Monotonic Network architecture

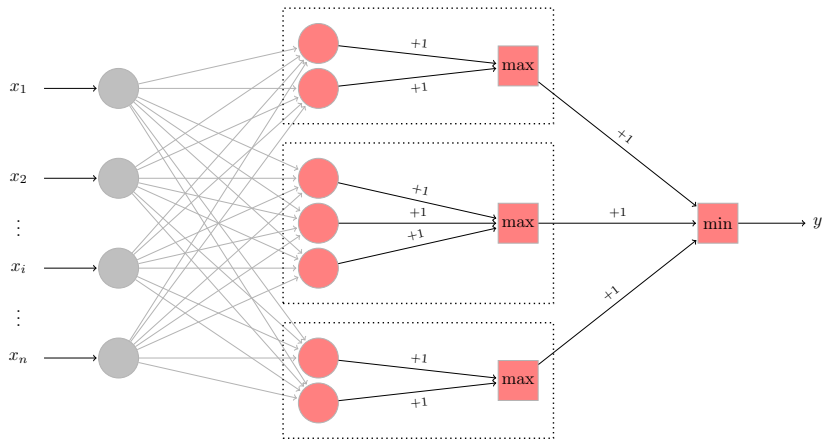


Figure: Monotonic network by Sill¹. The gray edges correspond to nonnegative weights.

¹Sill, J. "Monotonic Networks". In: *Adv. in NeurIPS*. 1998.

$$y = f(\mathbf{x}) = \bigwedge_{k \in [K]} \bigvee_{j \in [J]} \{\mathbf{w}_{k,j}^T \mathbf{x} + b_{k,j}\}$$

- ▶ neither convex nor concave
- ▶ Monotonicity constraints $\rightarrow \mathbf{w} \in \mathbb{R}_{\geq 0}^n$
- ▶ corresponds to morphological closing
- ▶ invertible for positive weights \rightarrow morphological opening

$$x = f^{-1}(y) = \bigvee_{k \in [K]} \bigwedge_{j \in [J]} \{w_{k,j}^{-1}(y - b_{k,j})\}$$

- ▶ Used softened morphological operators
- ▶ Active group: affine term that determines the output for pattern $\mathbf{x} \in \mathbb{R}^n$
- ▶ “Hard” operators \rightarrow 1 – 1 correspondence between active group and output
 - \rightarrow only active hyperplane gets updated
 - \rightarrow a small fraction of hyperplanes dominate the training
- ▶ “Soft” operators alleviate undifferentiability \rightarrow better approximation

Experiment Description

- ▶ strictly increasing function $f(x) = x^3 + x + \sin x, x \in [-4, 4]$
- ▶ scale both the domain and the image of f to $[-1, 1]$
- ▶ 100 observations uniformly and corrupt them with additive i.i.d zero-mean Gaussian noise $\varepsilon \sim \mathcal{N}(0, \sigma^2)$
- ▶ Glorot uniform initialization¹ for all network parameters

¹Glorot, X. and Bengio, Y. "Understanding the difficulty of training deep feedforward neural networks". In: *Proc. 13th Int'l Conf. Artificial Intelligence & Statistics*. 2010.

σ	0.05	0.1	0.15	0.2
Linear Reg.	0.0236	0.03077	0.04827	0.0505
Isotonic Reg. ¹	0.0042	0.01112	0.02557	0.0417
Sill Net ²	0.00305	0.01107	0.02401	0.0390
Smooth Sill Net [ours]	0.00294	0.00938	0.02302	0.0386

Table: RMS error of monotonic regression methods with noise $\varepsilon \sim \mathcal{N}(0, \sigma^2)$

¹Barlow, R. E. and Brunk, H. D. "The Isotonic Regression Problem and its Dual". In: *J. Amer. Stat. Assoc.* 67.337 (1972), pp. 140–147.

²Sill, J. "Monotonic Networks". In: *Adv. in NeuIPS*. 1998.

Results

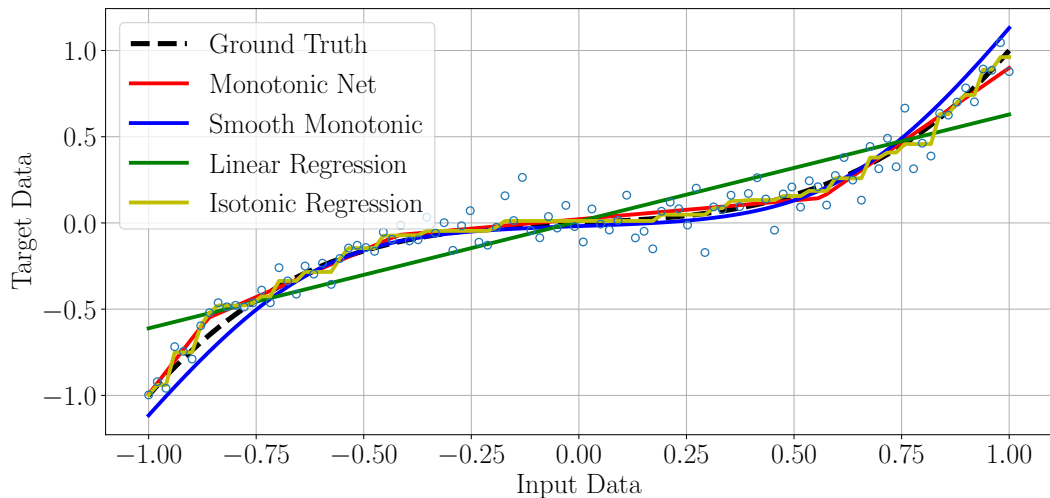


Figure: Comparison of monotonic regression methods
Smooth Monotonic is ours.

- ▶ Extended Binary Morphological Classifiers trained via CCP to multiclass problems
- ▶ Studied the sparsity of Morphological Neural Nets and showed their superior compression ability compared to their linear counterparts
- ▶ Improved convergence and accuracy of monotonic regression with softened morphological operators based on Maslov Dequantization

For a complete list of references please see the paper.

Thank you for your attention!