Mehdi Khamassi Short CV

Tenured Research Scientist (CR1 CNRS) Institute of Intelligent Systems and Robotics (ISIR) Université Pierre et Marie Curie (UPMC) – BC 173 4 place Jussieu, 75005 Paris, France mehdi.khamassi (at) upmc.fr

Webpage & full CV http://people.isir.upmc.fr/khamassi

Researcher IDs Scholar Page, Orcid 0000-0002-2515-1046, Scopus 6508136456

<u>Date/place of birth</u> 18 Jan. 1980 in Paris, France

Current position CR1 Centre National de la Recherche Scientifique (CNRS), section 7 "Information

Sciences" and interdisciplinary comity 51 "Modeling and Analysis of Biological

Data and Systems"

Affiliation Institute of Intelligent Systems and Robotics (ISIR)

CNRS / Université Pierre et Marie Curie (UPMC)

BC173, 4 place Jussieu, 75005 Paris

Other current positions Director of Studies for the Cogmaster program at Ecole Normale Supérieure, Paris

Co-animator of the "Robotics&Neuroscience" national working group (CNRS GDR)

Visiting Researcher at National Polytechnical University of Athens, Greece

Visiting Researcher at Department of Experimental Psychology, Oxford Univ., UK

Associate Editor for Frontiers in Neurorobotics and Intellectica

Education 2014 HDR (Habilitation to Direct Researches), UPMC, Paris, France

2007 PhD in Cognitive Neuroscience, UPMC, Paris, France

2003 MSc in Cognitive Sciences, UPMC/ENS/Polytechnique/EHESS, Paris, France

2003 MEng in Computer Science, ENSIIE, Evry, France

Research Experience 2013-2015 Visiting Researcher, Center for Mind/Brain Sciences, U Trento, Italy

2010-2014 CR2 CNRS Permanent Researcher, ISIR, UPMC, Paris, France 2008-2010 Post-doc, Stem-cell & Brain Institute, INSERM, Lyon, France

2008 (3m.) Guest Researcher, Okinawa Institute of Science & Technology, Japan 2007-2008 Post-doc, Laboratory of Computer Science, UPMC, Paris, France

2003-2007 PhD student, Collège de France, Paris, France

Invited talks 39 invited talks (including 13 at international conf/symp/colloq, 2 keynotes)

Project experience PI of Sorbonnes Universités Robot-Parallearning Project (2015-2016); Co-PI of

several national (ANR, CNRS) and internationals (ANR-NSF, Royal Society-CNRS)

projects; Participant to 5 EU projects and numerous national ones.

Event organization Co-organizer of 6 international top-level meetings on decision-making, including

yearly Symp. on Biology of Decision-Making (200 participants, 80 posters, 30 talks), 8 one-day national symposia on Robotics & Neuroscience (50 participants).

<u>Student supervision</u> Supervised 4 completed PhDs; 3 ongoing ones; 1 post-doc; 19 Master/Eng students.

Publication record 26 journal articles, 1 edited journal special issue, 16 peer-reviewed international

conference papers, 4 book chapters incl. MIT Press, Oxford Univ Press, 57 other pub.

Awards 2 best paper awards (International SAB Conf 2012; La Recherche Prize 2010).

Teaching 2 created courses (Robotics at Cogmaster program at ENS; Critical thinking at

UPMC); Annual invited courses at Polytechnique, ENS, UPMC, U Orsay, U Lyon 1.

Other responsibilities Member of the executive committee of the SMART Labex, 8 years / 5M€ transverse

laboratory gathering 8 UPMC research institutes, including ISIR (since 2012);

Evaluation comity member for 3 associate professor recruitments at UPMC / CNRS,

Univ. Cergy-Pontoise / ENSEA and Univ. Lorraine / INRIA;

President of the jury for 1 PhD thesis evaluation committee, Examiner/Reviewer for 10 PhD theses evaluation committees, 1 Habilitation to Direct Research evaluation

committee, and 7 mid-term PhD theses evaluation committees.

10 selected publications (PhD supervisors [Sidney I. Wiener, Agnès Guillot] in italic letters):

Renaudo, E., Girard, B., Devin, S., Alami, R., Clodic, A., Chatila, C. and <u>Khamassi, M.</u> Can robots learn behavioral habits? Coordination of model-based and model-free reinforcement learning in a robot neuro-inspired cognitive architecture. Submitted to **Frontiers in Neurorobotics**.

Khamassi, M., Girard, B., Clodic, A., Devin, S., Renaudo, E., Pacherie, E., Alami, R. and Chatila, R. (2016). Integration of action, joint action & learning in robot cognitive architectures. **Intellectica**, 65(1):169-203.

## Mehdi Khamassi

**Short CV** 

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- Palminteri, S., <u>Khamassi, M.</u>, Joffily, M. and Coricelli, G. (2015). The neural computation of value contextualization in reward and punishment learning. **Nature Communications**, 6:8096.
- <u>Khamassi, M.</u>, Quilodran, R., Enel, P., Dominey, P.F. and Procyk, E. (2015). Behavioral regulation and the modulation of information coding in the lateral prefrontal and cingulate cortex. **Cerebral Cortex**, 25(9):3197-218.
- Lesaint, F., Sigaud, O., Flagel, S.B., Robinson, T.E. and <u>Khamassi, M.</u> (2014). Modelling individual differences observed in Pavlovian autoshaping in rats using a dual learning systems approach and factored representations. **PLoS Computational Biology**, 10(2):e1003466.
- <u>Khamassi, M.</u>, Enel, P., Dominey, P.F. and Procyk, E. (2013). Medial prefrontal cortex and the adaptive regulation of reinforcement learning parameters. **Progress in Brain Research**, 202:441-464.
- Caluwaerts, K., Staffa, M., N'Guyen, S., Grand, C., Dollé, L., Favre-Félix, A., Girard, B. and <u>Khamassi, M.</u> (2012). A biologically inspired meta-control navigation system for the Psikharpax rat robot. **Bioinspiration & Biomimetics**, 7(2):025009.
- <u>Khamassi, M.</u> and Humphries, M.D. (2012), Integrating cortico-limbic-basal ganglia architectures for learning model-based and model-free navigation strategies, **Frontiers in Behav. Neuroscience**, 6-79.
- <u>Khamassi, M.</u>, Lallée, S., Enel, P., Procyk, E. and Dominey P.F. (2011). Robot cognitive control with a neurophysiologically inspired reinforcement learning model. **Frontiers in Neurorobotics**, 5:1.
- Peyrache, A., <u>Khamassi, M.</u>, Benchenane, K., *Wiener, S.I.* and Battaglia, F.P. (2009). Replay of rule-learning related neural patterns in the prefrontal cortex during sleep. **Nature Neuroscience**, 12(7):919-926.

## 10 selected invited talks:

- 2017: Panel at the 50<sup>th</sup> Winter Conference on Brain Research, Big Sky, USA
- 2016: "Addiction, in theory" meeting, Gatsby Unit, University College London, London, UK
- 2016: 6th International Symposium on Motivational and Cognitive Control (Plenary), St Andrews, UK
- 2016: 6<sup>th</sup> International Symposium on Biology of Decision-Making (Plenary), **Paris, France**
- 2015: 3<sup>rd</sup> International Conference on Cognition, Brain & Computation (Plenary), Ahmedabad, India
- 2015: International Conf. on Computational Intelligence (Keynote), Visakhapatnam, India
- 2015: International Conf. on Cognition in Smart Cities (Keynote), Vizag, India
- 2014: Symposium at International Cognitive Neuroscience Conference, Brisbane, Australia
- 2013: Harvard Summer Program in Trento, Center for Mind/Brain Sciences, Trento, Italy
- 2012: Neuromorphic Engineering Summerschool/Workshop, Telluride, USA

## 5 selected collaborative research projects:

2016-2019	ANR-NSF Collaborative Research in Computational Neuroscience -
	"Neurobehavioral assessment of a computational model of reward learning" (role: co-
	PI with Matt R. Roesch (PI), Alain Marchand) – Total: 670 K\$ (123 K\$ for the team)
2015-2018	European Union H2020-ICT-2014 – "DREAM: Deferred Restructuring of
	Experience in Autonomous Machines" (role: participant with Stéphane Doncieux (PI)
	et al.) – Total: 2784 K€ (758 K€ for the team)
2015-2016	Sorbonne-Universités ANR-11-IDEX-0004-02 Idex SUPER SU-15-R-PERSU-14
	PERSU – "ROBOT PARALLEARNING, Neuro-inspired coordination of parallel
	learning processes in robots" (role: PI) – Total direct costs: 70 K€ (for the team)
2013-2016	Agence Nationale de la Recherche ANR-12-CORD-0030 (CONTINT) -
	"ROBOERGOSUM, Robot Self-Awareness" (role: co-PI with Rachid Alami, Benoît
	Girard, Raja Chatila (PI)) – Total direct costs: 422 K€ (258 K€ for the team)
2011-2015	Agence Nationale de la Recherche ANR-11-BSV4-006 – "Learning Under
	Uncertainty" (role: co-PI with Paul Apicella, Etienne Coutureau, Benoît Girard, Alain
	Marchand, Emmanuel Procyk (PI)) – Total direct costs: 616 K€ (73 K€ for the team)